

Internal-variable modelling of solids with slow dynamics

Harold Benjamin¹, Guillaume Chiavassa²,
Nicolas Favrie³, Bruno Lombard¹, Emmanuelle Sarrouy¹

¹Laboratoire de Mécanique et d'Acoustique, Marseille (France)

berjamin@lma.cnrs-mrs.fr   

²Laboratoire de Mécanique, Modélisation et Procédés Propres, Marseille (France)

³Institut Universitaire des Systèmes Thermiques Industriels, Marseille (France)

Modelling group seminar, NUI Galway, September 28, 2018



Who I am

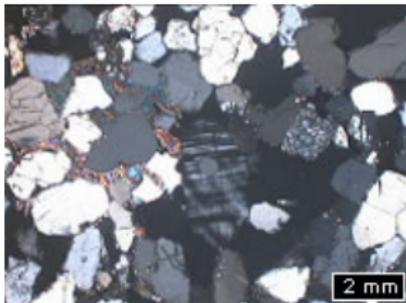
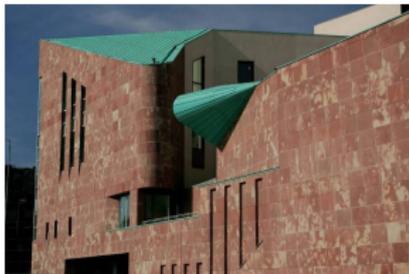
26, French and German

École Centrale de Marseille: *general engineering*, acoustics

PhD viva: 29th November 2018

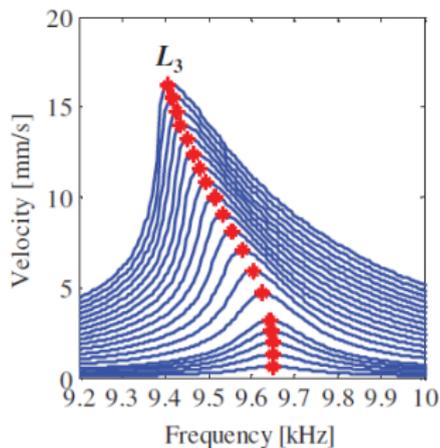
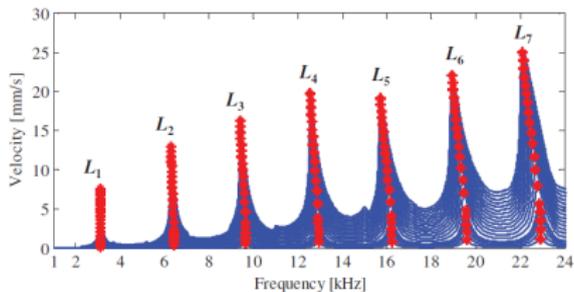


Sandstone across the scales



Forced longitudinal vibrations (1)

Resonance (NRUS)  *Johnson 96, Remillieux 16*

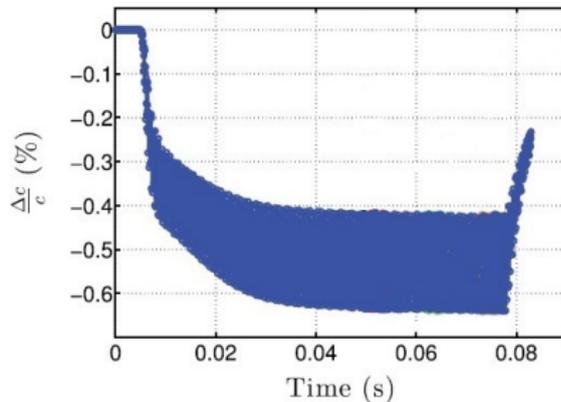
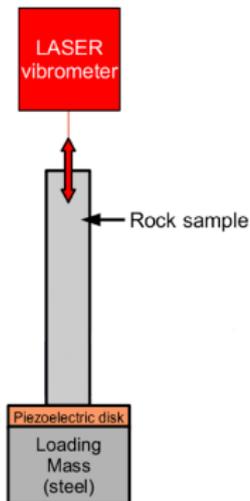


Measurement of *steady-state* frequency response

- low strain $\varepsilon \sim 10^{-8} \rightarrow 10^{-6}$
- softening (\simeq Duffing)  *TenCate et al. 04*
- harmonic generation

Forced longitudinal vibrations (2)

Dynamic Acoustoelasticity (DAE) 📖 *Renaud et al. 12, Rivière et al. 13*

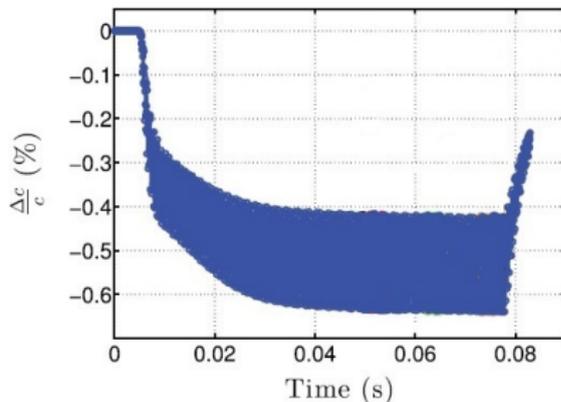
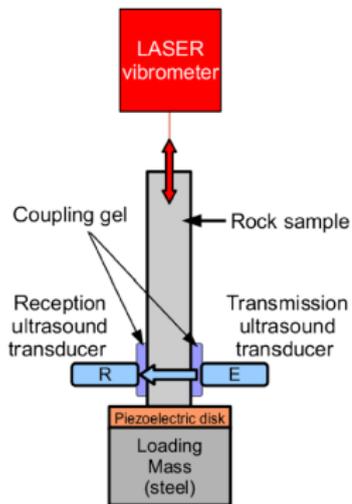


Local measurement over *time*

- softening/recovery *transients* (“slow dynamics”)
- no permanent damage

Forced longitudinal vibrations (2)

Dynamic Acoustoelasticity (DAE) 📖 *Renaud et al. 12, Rivière et al. 13*

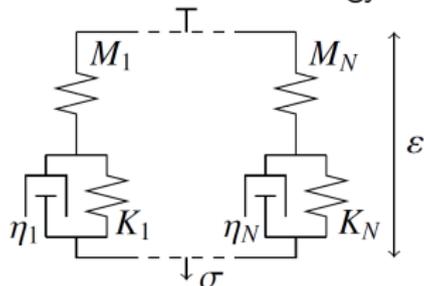


Local measurement over time

- softening/recovery *transients* (“slow dynamics”)
- no permanent damage

Contribution

Generalized Zener rheology



Softening (internal variable)

$$\sigma = (1 - g)E\varepsilon, \quad \varepsilon = \partial_x u$$

$$\tau \dot{g} = \frac{1}{2}E\varepsilon^2 - \gamma g$$

$$\varepsilon \sim 10^{-8}$$

$$\varepsilon \sim 10^{-6}$$

Outline

- ① Modelling
- ② Time-domain numerical method
- ③ Frequency-domain numerical method

Outline

- ① Modelling
- ② Time-domain numerical method
- ③ Frequency-domain numerical method

Thermodynamics with internal variable

Adiabatic transformation

Variables of state $\{s, \varepsilon, \mathbf{g}\}$ (elasticity + internal variable)

Clausius–Duhem inequality

$$\left(\sigma - \frac{\partial U}{\partial \varepsilon}\right)\dot{\varepsilon} - \frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0 \quad \text{for all} \quad \{\varepsilon, \mathbf{g}, \dot{\varepsilon}\}$$

$$\implies \quad \sigma = \frac{\partial U}{\partial \varepsilon} \quad \text{and} \quad -\frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0$$

Thermodynamics with internal variable

Adiabatic transformation

Variables of state $\{s, \varepsilon, \mathbf{g}\}$ (elasticity + internal variable)

Clausius–Duhem inequality

$$\left(\sigma - \frac{\partial U}{\partial \varepsilon}\right)\dot{\varepsilon} - \frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0 \quad \text{for all} \quad \{\varepsilon, \mathbf{g}, \dot{\varepsilon}\}$$

$$\implies \boxed{\sigma = \frac{\partial U}{\partial \varepsilon}} \quad \text{and} \quad -\frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0$$

If $\boxed{\sigma = \phi_1(\mathbf{g})W'(\varepsilon)}$, then

$$\boxed{U = \phi_1(\mathbf{g})W(\varepsilon) + \phi_2(\mathbf{g})} \quad \text{and} \quad -(\phi_1'(\mathbf{g})W(\varepsilon) + \phi_2'(\mathbf{g}))\dot{\mathbf{g}} \geq 0$$

Choice: $\tau\dot{\mathbf{g}} = -(\phi_1'(\mathbf{g})W(\varepsilon) + \phi_2'(\mathbf{g}))$ with $\tau > 0$

Thermodynamics with internal variable

Adiabatic transformation

Variables of state $\{s, \varepsilon, g\}$ (elasticity + internal variable)

Clausius–Duhem inequality

$$\left(\sigma - \frac{\partial U}{\partial \varepsilon}\right)\dot{\varepsilon} - \frac{\partial U}{\partial g}\dot{g} \geq 0 \quad \text{for all} \quad \{\varepsilon, g, \dot{\varepsilon}\}$$

$$\implies \quad \sigma = \frac{\partial U}{\partial \varepsilon} \quad \text{and} \quad \boxed{-\frac{\partial U}{\partial g}\dot{g} \geq 0}$$

If $\sigma = \phi_1(g)W'(\varepsilon)$, then

$$\boxed{U = \phi_1(g)W(\varepsilon) + \phi_2(g)} \quad \text{and} \quad \boxed{-(\phi_1'(g)W(\varepsilon) + \phi_2'(g))\dot{g} \geq 0}$$

Choice: $\tau\dot{g} = -(\phi_1'(g)W(\varepsilon) + \phi_2'(g))$ with $\tau > 0$

Thermodynamics with internal variable

Adiabatic transformation

Variables of state $\{s, \varepsilon, \mathbf{g}\}$ (elasticity + internal variable)

Clausius–Duhem inequality

$$\left(\sigma - \frac{\partial U}{\partial \varepsilon}\right)\dot{\varepsilon} - \frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0 \quad \text{for all} \quad \{\varepsilon, \mathbf{g}, \dot{\varepsilon}\}$$

$$\implies \quad \sigma = \frac{\partial U}{\partial \varepsilon} \quad \text{and} \quad -\frac{\partial U}{\partial \mathbf{g}}\dot{\mathbf{g}} \geq 0$$

If $\sigma = \phi_1(\mathbf{g})W'(\varepsilon)$, then

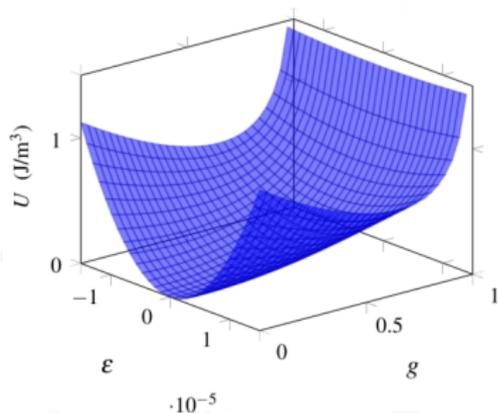
$$U = \phi_1(\mathbf{g})W(\varepsilon) + \phi_2(\mathbf{g}) \quad \text{and} \quad -(\phi_1'(\mathbf{g})W(\varepsilon) + \phi_2'(\mathbf{g}))\dot{\mathbf{g}} \geq 0$$

Choice: $\tau\dot{\mathbf{g}} = -(\phi_1'(\mathbf{g})W(\varepsilon) + \phi_2'(\mathbf{g}))$ with $\tau > 0$

Modelling choices

From  *Berjamin et al. 17*

- mathematical considerations
- qualitative behaviour



Internal energy $U = \phi_1(g)W(\varepsilon) + \phi_2(g)$

Possible choices:

$$W(\varepsilon) \simeq \frac{1}{2}E\varepsilon^2$$

$$\phi_1(g) = 1 - g \text{ for } g < 1$$

$$\phi_2(g) \simeq \frac{1}{2}\gamma g^2$$

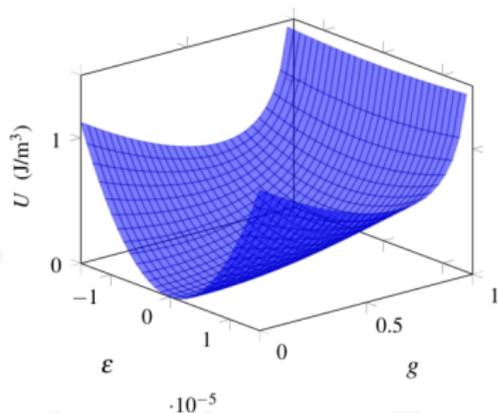
$$\sigma = \phi_1(g)W'(\varepsilon)$$

$$\tau \dot{g} = -(\phi_1'(g)W(\varepsilon) + \phi_2'(g))$$

Modelling choices

From  *Berjamin et al. 17*

- mathematical considerations
- qualitative behaviour



Internal energy $U = \phi_1(g)W(\varepsilon) + \phi_2(g)$

Possible choices:

$$W(\varepsilon) \simeq \frac{1}{2}E\varepsilon^2$$

$$\phi_1(g) = 1 - g \text{ for } g < 1$$

$$\phi_2(g) \simeq \frac{1}{2}\gamma g^2$$

$$\sigma = (1 - g)E\varepsilon$$

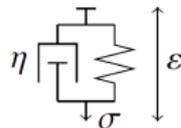
$$\tau\dot{g} = \frac{1}{2}E\varepsilon^2 - \gamma g$$

Viscoelastic cases

Kelvin–Voigt rheology $\{s, \varepsilon, \dot{\varepsilon}, g\}$

$$\sigma = (1 - g)(E\varepsilon + \eta\dot{\varepsilon})$$

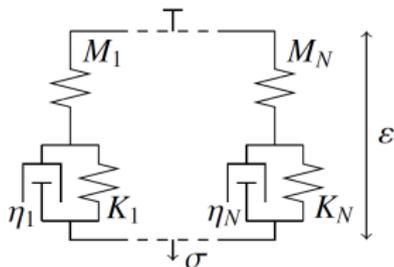
$$\tau\dot{g} = \frac{1}{2}E\varepsilon^2 - \gamma g$$

Generalized Zener rheology $\{s, \varepsilon, \varepsilon - \xi_1, \dots, \varepsilon - \xi_N, g\}$  Benjamin et al. 18

$$\sigma = (1 - g) \sum_{\ell=1}^N M_{\ell} \xi_{\ell}$$

$$\tau\dot{g} = \frac{1}{2} \left(\sum_{\ell=1}^N M_{\ell} (\xi_{\ell})^2 + K_{\ell} (\varepsilon - \xi_{\ell})^2 \right) - \gamma g$$

$$\eta_{\ell} \dot{\xi}_{\ell} = \eta_{\ell} \dot{\varepsilon} + K_{\ell} \varepsilon - (M_{\ell} + K_{\ell}) \xi_{\ell}$$



Outline

- ① Modelling
- ② Time-domain numerical method
- ③ Frequency-domain numerical method

Lagrangian equations of motion

First-order strong formulation  *Benjamin et al. 18*

$$\begin{cases} \partial_t \varepsilon = \partial_x v \\ \rho_0 \partial_t v = \partial_x \sigma \end{cases}$$

and

$$\left\{ \begin{array}{l} \sigma = (1 - g) \sum_{\ell=1}^N M_\ell \xi_\ell \\ \tau \partial_t g = \frac{1}{2} \left(\sum_{\ell=1}^N M_\ell (\xi_\ell)^2 + K_\ell (\varepsilon - \xi_\ell)^2 \right) - \gamma g \\ \eta_\ell \partial_t \xi_\ell = \eta_\ell \partial_t \varepsilon + K_\ell \varepsilon - (M_\ell + K_\ell) \xi_\ell \end{array} \right.$$

Balance laws $\partial_t \mathbf{q} + \partial_x \mathbf{f}(\mathbf{q}) = \mathbf{r}(\mathbf{q})$, with sound speeds

$$\{-c, 0, \dots, 0, +c\} \quad \text{where} \quad \rho_0 c^2 = (1 - g) \sum_{\ell=1}^N M_\ell$$

Finite-volume method  *LeVeque 02*

Finite-volume method

Operator splitting 📖 *Berjamin et al. 18*

$$\partial_t \mathbf{q} + \partial_x \mathbf{f}(\mathbf{q}) = \mathbf{r}(\mathbf{q}) \quad \text{as} \quad \begin{aligned} (\mathcal{H}_a) : \quad & \partial_t \mathbf{q} + \partial_x \mathbf{f}(\mathbf{q}) = \mathbf{0} \\ (\mathcal{H}_b) : \quad & \partial_t \mathbf{q} = \mathbf{r}(\mathbf{q}) \end{aligned}$$

Strang splitting scheme

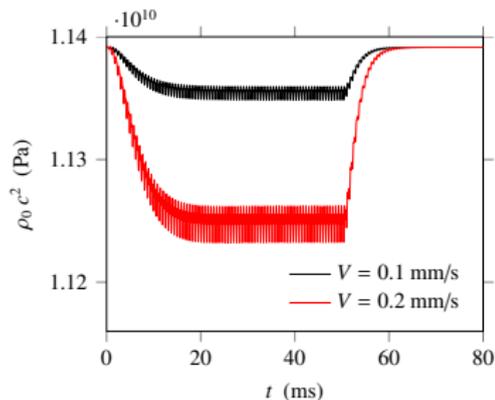
- (\mathcal{H}_a) : fourth-order ADER flux
- (\mathcal{H}_b) : fourth-order adaptive Rosenbrock method

Configuration



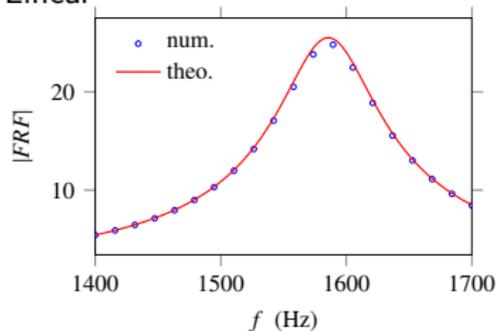
Results

Dynamic Acoustoelasticity

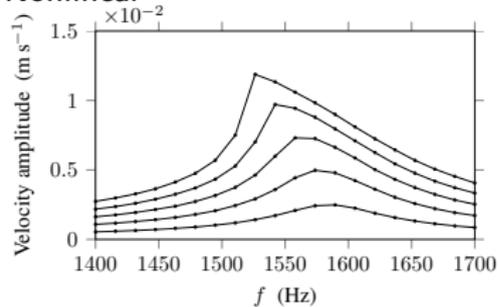
20 freq. \simeq 40 min. \rightarrow

Resonance curves

Linear



Nonlinear



Outline

- ① Modelling
- ② Time-domain numerical method
- ③ Frequency-domain numerical method

Lagrangian equations of motion

Second-order-in-time weak formulation

$$\rho_0 \langle \partial_{tt} u, \tilde{u} \rangle = (\sigma \tilde{u})|_{x=L} - (\sigma \tilde{u})|_{x=0} - \langle \sigma, \partial_x \tilde{u} \rangle$$

for all $\tilde{u} \in H^1([0, L])$, and

$$\begin{cases} \sigma = (1 - g) \sum_{\ell=1}^N M_\ell \xi_\ell \\ \tau \partial_t g = \frac{1}{2} \left(\sum_{\ell=1}^N M_\ell (\xi_\ell)^2 + K_\ell (\varepsilon - \xi_\ell)^2 \right) - \gamma g \\ \eta_\ell \partial_t \xi_\ell = \eta_\ell \partial_t \varepsilon + K_\ell \varepsilon - (M_\ell + K_\ell) \xi_\ell \end{cases}$$

Mixed finite elements (P^1 - P^0) yield $\dot{\mathbf{X}} = \mathbf{C} + \mathbf{LX} + \mathbf{Q} : (\mathbf{X}\mathbf{X}^\top)$

Harmonic balance + numerical continuation (Manlab)  *Cochelin et al. 09*

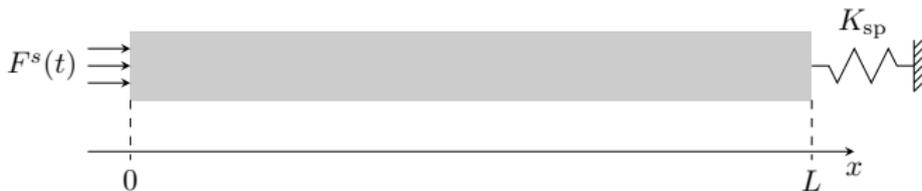
Harmonic balance + numerical continuation (Manlab)

Harmonic balance of $\dot{\mathbf{X}} = \mathbf{C} + \mathbf{L}\mathbf{X} + \mathbf{Q} : (\mathbf{X}\mathbf{X}^\top)$ 📖 *Cochelin et al. 09*

$$\mathbf{X} = \frac{\mathbf{a}_0}{2} + \mathbf{a}_1 \cos(\omega t) + \mathbf{b}_1 \sin(\omega t) + \dots + \mathbf{b}_H \sin(H\omega t)$$

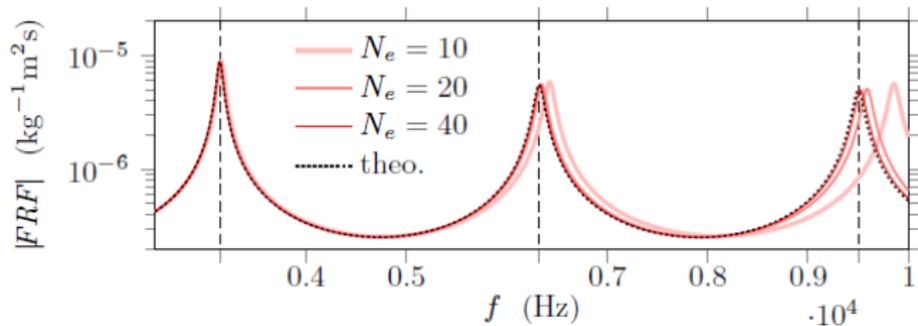
Numerical continuation: Analytic expansion of $\mathbf{a}_0, \dots, \mathbf{b}_H$ w.r.t. parameter

Configuration

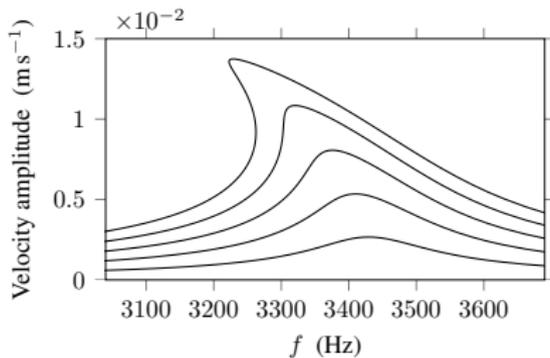


Resonance curves

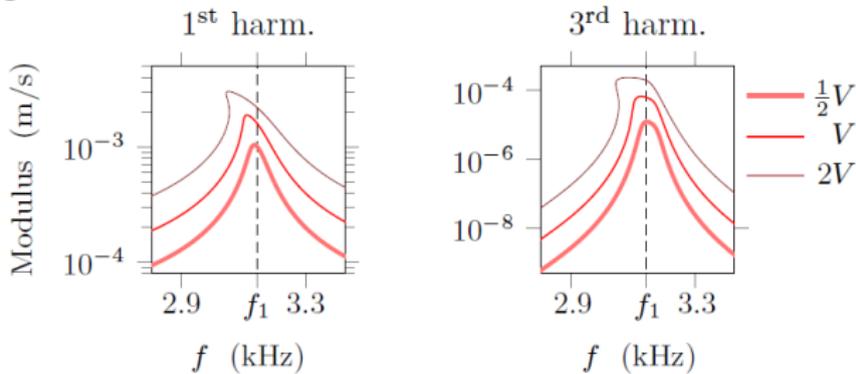
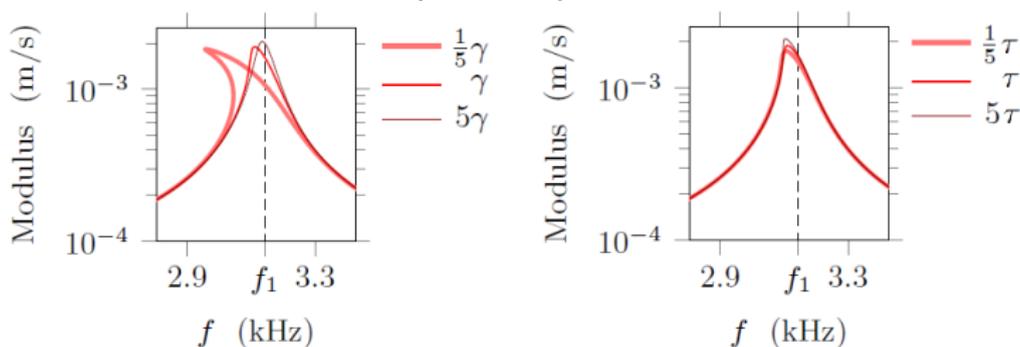
Linear



Nonlinear

continuous freq. $\simeq 40$ sec. \rightarrow

Harmonic generation

Parametric study $\tau \dot{g} = W - \gamma g$ (1st harm.)

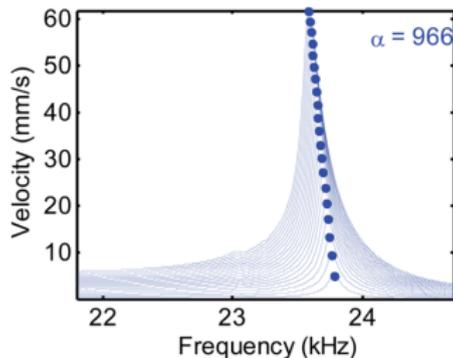
Conclusion

Rocks and concrete belong to a general class of *nonlinear viscoelastic solids with softening*

	response (stress BC)	response (displ. BC)	transient
time FVM	✗	(✗)	✓
freq. FEM	✓	(✓)	✗

Future works

- continuation of peaks (backbone curve)
- perturbation methods



Multiple space dimensions (non viscous)

$$\sigma = (1 - g) \frac{1}{\det \mathbf{F}} \mathbf{F} \cdot \frac{\partial W}{\partial \mathbf{E}} \cdot \mathbf{F}^\top$$

$$\tau \dot{g} = W(\mathbf{E}) - \gamma g$$

$$W(\mathbf{E}) = \frac{\lambda}{2} (\text{tr } \mathbf{E})^2 + \mu \text{tr } \mathbf{E}^2 + \frac{C}{3} (\text{tr } \mathbf{E})^3$$

$$+ \mathcal{B} (\text{tr } \mathbf{E}) \text{tr } \mathbf{E}^2 + \frac{\mathcal{A}}{3} \text{tr } \mathbf{E}^3 + \dots$$

