

Static Equilibrium Equations of a Model Red Blood Cell

Modelling
Research
Group

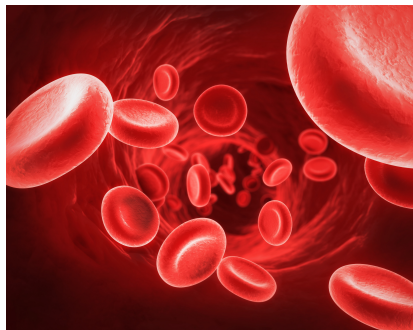


Paul Greaney

20 November 2015

Introduction

- Mature red blood cell has a biconcave shape
- Adding water to plasma causes swelling
- Becomes ellipsoidal, eventually spherical
- Initial formation is reverse of this process
- Sphere buckles under excess of internal pressure



The Free Energy

Jenkins (1977): Only free energy function compatible with fluidity of surface and unaffected by rigid rotations depends at most on h and k .

Simplest form for free energy density of a surface is

$$w(h, k) = ch^2 + c_1 k \quad (1)$$

where h and k are mean and total curvatures of the surface.
Total energy is

$$W = \int_A w \, dA \quad (2)$$

The Free Energy

Considering variations in the energy and associated quantities, gives the normal equilibrium equation

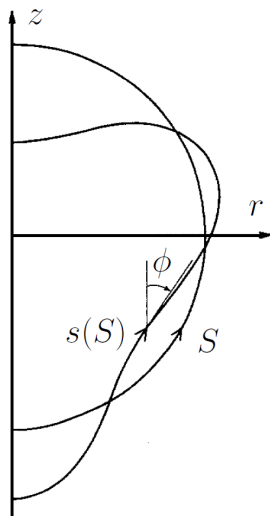
$$2h(\bar{d} + c(h^2 - k)) + c\partial_a(g^{ab}\partial_b h) = -\bar{p}, \quad (3)$$

where g^{ab} is the inverse of g_{ab} , the *first fundamental form*; d is a constant; and \bar{p} is the difference between exterior and interior pressure.

Axisymmetric Deformations

Material parameters:

- Azimuthal angle θ
- Arc length S from axis of symmetry on sphere.
- Arc length on deformed surface is $s = s(S)$
- $\phi = \phi(S)$ is the angle between the tangent to a line $\theta = \text{constant}$ and the axis of symmetry.



Axisymmetric Deformations

$$\mathbf{X} = r(S)(\cos(\theta)\hat{\mathbf{i}} + \sin(\theta)\hat{\mathbf{j}}) + z(S)\hat{\mathbf{k}} \quad (4)$$

Tangent vectors

$$\mathbf{e}_\theta = \partial_\theta \mathbf{X} = r(-\sin(\theta)\hat{\mathbf{i}} + \cos(\theta)\hat{\mathbf{j}}), \quad (5)$$

$$\mathbf{e}_S = \partial_S \mathbf{X} = \dot{s} \left(\sin(\phi) \left(\cos(\theta)\hat{\mathbf{i}} + \sin(\theta)\hat{\mathbf{j}} \right) + \cos(\phi)\hat{\mathbf{k}} \right), \quad (6)$$

with unit normal

$$\begin{aligned} \mathbf{n} &= \frac{\mathbf{e}_\theta \times \mathbf{e}_S}{|\mathbf{e}_\theta \times \mathbf{e}_S|} \\ &= \cos(\theta) \cos(\phi)\hat{\mathbf{i}} + \sin(\theta) \cos(\phi)\hat{\mathbf{j}} - \sin(\phi)\hat{\mathbf{k}}. \end{aligned} \quad (7)$$

Calculating g_{ab} (with components $\mathbf{e}_a \cdot \mathbf{e}_b$) and the second fundamental form k_{ab} (with components $-\partial_a \mathbf{n} \cdot \mathbf{e}_b$) allows us to calculate the curvatures

$$\begin{aligned}
 k &= \det k_b^a = \det(k_{bc} g^{ca}) \\
 &= \begin{vmatrix} \frac{-\cos \phi}{r} & 0 \\ 0 & \frac{r \dot{\phi}}{R} \end{vmatrix} \\
 &= \dot{\phi} \frac{\cos \phi}{R}, \tag{8}
 \end{aligned}$$

$$\begin{aligned}
 h &= \frac{1}{2} k_a^a \\
 &= \frac{1}{2} (k_1^1 + k_2^2) \\
 &= \frac{1}{2} \left(\frac{r \dot{\phi}}{R} - \frac{\cos \phi}{r} \right). \tag{9}
 \end{aligned}$$

Axisymmetric Deformations

Eliminating k , introducing transverse shear $q = \dot{h} \frac{r^2}{\sin^2(S)}$ gives

$$\dot{h} = \frac{\sin^2(S)}{r^2} q. \quad (10)$$

$$\dot{q} = -2h \left[d + h^2 + \frac{\cos \phi}{r} \left(2h + \frac{\cos(\phi)}{r} \right) \right] - p. \quad (11)$$

$$\dot{\phi} = \frac{2 \sin(S)}{r} h + \frac{\sin(S)}{r^2} \cos(\phi), \quad (12)$$

$$\dot{r} = \frac{\sin(S)}{r} \sin(\phi), \quad (13)$$

$$\dot{z} = \frac{\sin(S)}{r} \cos(\phi), \quad (14)$$

$$(15)$$

$$q(0) = q(\pi) = 0, \phi(0) = \frac{\pi}{2}, \phi(\pi) = -\frac{\pi}{2}, r(0) = 0, z\left(\frac{\pi}{2}\right) = 0, \quad (16)$$

We expand $r \sim r_0(S) + \epsilon r_1(S)$ etc. to give

$$\ddot{h}_1 + \cot(S)\dot{h}_1 + ph_1 = 2d_1, \quad (17)$$

$$\dot{r}_1 = \phi_1 \sin(S) - r_1 \cot(S), \quad (18)$$

$$\dot{z}_1 = \phi_1 \cos(S) - r_1, \quad (19)$$

$$\dot{\phi}_1 = 2h_1 - \phi_1 \cot(S), \quad (20)$$

with

$$\dot{h}_1(0) = \dot{h}_1(\pi) = \phi_1(0) = \phi_1(\pi) = r_1(0) = z_1\left(\frac{\pi}{2}\right) = 0. \quad (21)$$

Solutions for h_1 compatible with the boundary conditions are

$h_1 = P_l(\cos(S))$, with $p = l(l + 1)$, $l = 2, 3, \dots$

For $l = 2$ we have $p = 6$ so

$$h_1 = \frac{1}{2}(3 \cos^2(S) - 1), \quad (22)$$

$$\phi_1 = \sin(S) \cos(S), \quad (23)$$

$$r_1 = \frac{1}{4} \sin^3(S), \quad (24)$$

$$z_1 = \frac{1}{16} \cos(S) + \frac{5}{48} \cos(3S); \quad (25)$$

we add these to the known quantities h_0, ϕ_0, r_0, z_0 for the sphere, ...

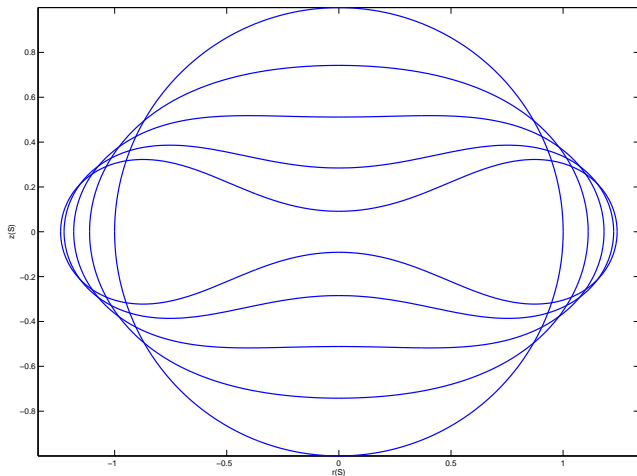


Figure: Cross sections of the axisymmetric deformation for $p = 6.0$ (spherical), 6.5, 7.0, 7.5, 7.9; deformation increases with pressure



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Static Equilibrium Configurations of a Model Red Blood Cell.

Journal of Mathematical Biology, 1977, **4**, 149–169



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SIAM J. Appl. Math., **32** (4), 755–764.