

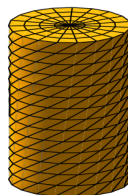
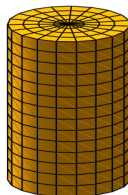
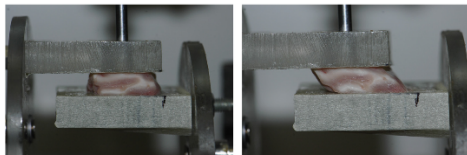
# Solids with a linear response in simple shear and torsion

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# Simple shear and torsion

- Many soft materials have a linear stress response in simple shear and in torsion, including rubbers and soft tissues.



# Simple shear and torsion

It can be shown that the Cauchy shear stress component  $T_{12}$  for simple shear is

$$T_{12} = 2 \left( \frac{\partial W}{\partial I_1} + \frac{\partial W}{\partial I_2} \right) K, \quad (1)$$

where  $K$  is the amount of shear,  $W$  is the strain energy and  $I_1, I_2$  are principal invariants, and that the torque  $M$  for torsion of a cylinder is

$$M = 4\pi\psi \int_0^a r^3 \left( \frac{\partial W}{\partial I_1} + \frac{\partial W}{\partial I_2} \right) dr, \quad (2)$$

where  $\psi$  is the amount of twist,  $r$  is the radial distance and  $a$  is the radius of the cylinder.

# Mooney-Rivlin model

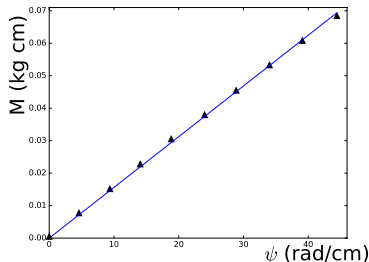
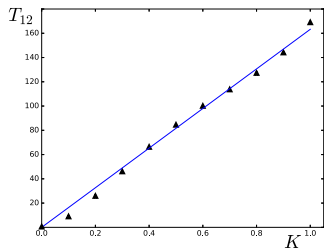
The Mooney-Rivlin model

$$W_{\text{MR}} = \frac{1}{2}C_1(I_1 - 3) + \frac{1}{2}C_2(I_2 - 3), \quad (3)$$

predicts a linear response in simple shear with

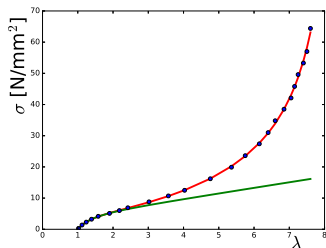
$$T_{12} = (C_1 + C_2)K, \quad (4)$$

where  $C_1, C_2$  are material parameters.



# Mooney-Rivlin model

However, the Mooney-Rivlin model is not capable of capturing more complex behaviours like the upturn which occurs for the extension of a solid (strain-stiffening effect).



# Derivation

In order to derive a strain energy  $W$  which leads to the desired linear response, we require

$$\frac{\partial W}{\partial I_1} + \frac{\partial W}{\partial I_2} = \text{const} = \frac{\mu}{2}. \quad (5)$$

where  $\mu$  is the shear modulus.

Note that the Mooney-Rivlin model is a particular solution of this equation with  $C_1 + C_2 = \mu$ .

Thus the general solution may be written as

$$W = W_{\text{MR}} + H(I_1, I_2). \quad (6)$$

Then, after substitution, we obtain a homogeneous partial differential equation for  $H$ ,

$$\frac{\partial H}{\partial I_1} + \frac{\partial H}{\partial I_2} = 0. \quad (7)$$

The general solution of this equation is simply  $H = H(I_1 - I_2)$ . We call the corresponding class of solids, the *generalized Mooney-Rivlin materials*,

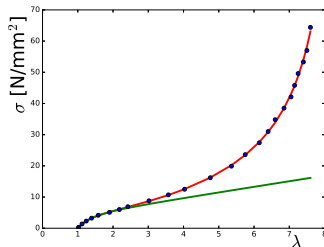
$$W = \frac{1}{2}C_1(I_1 - 3) + \frac{1}{2}C_2(I_2 - 3) + H(I_1 - I_2). \quad (8)$$

As an illustration we consider the following example of a generalized Mooney-Rivlin material,

$$W_{\text{gMR}} = \frac{1}{2}C_1(I_1 - 3) + \frac{1}{2}C_2(I_2 - 3) - \frac{1}{2}C_3J_m \ln \left( 1 - \frac{I_1 - I_2}{J_m} \right). \quad (9)$$

# Fitting





This model provides an excellent fit to the experimental data for extension of rubber.





- The particular model mentioned involves four parameters.
- It can be shown that the entire class of generalized Mooney-Rivlin materials is not capable of modelling non-linear shear wave propagation.

# References

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