

# Playing with elasticity

David Colson, Seán Hehir, Róisín Hill and Brian Regan

3rd Annual Stokes Modelling Workshop

June 16, 2016



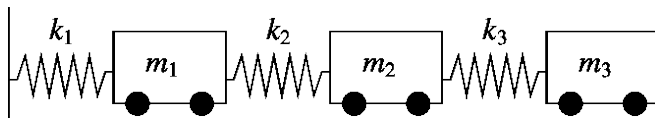
# Introduction

We have conducted an investigation into the string-bridge-soundboard systems of acoustic instruments.

We created a simplified model using classical mechanics, and then used it to gain intuition for the forces at play in the system.

# Basic Model

Our basic model is a three spring-mass system



$m_1$ : soundboard,       $m_2$ : bridge,       $m_3$ : string.

# Equations

Equations for the springs and masses

$$m_1 \ddot{x}_1 + k_1 x_1 + k_2(x_2 - x_1) - c_1 \dot{x}_1 + c_2(\dot{x}_2 - \dot{x}_1) = 0$$

$$m_2 \ddot{x}_2 + k_2(x_2 - x_1) - k_3(x_3 - x_2) - c_2(x_2 - x_1) + c_3(\dot{x}_3 - \dot{x}_2) = 0$$

$$m_3 \ddot{x}_3 + k_3(x_3 - x_2) - c_3(\dot{x}_3 - \dot{x}_2) - F = 0$$

where  $c_1$ ,  $c_2$  and  $c_3$  are the damping coefficients of springs 1,2, and 3 respectively.

# Solution

Solved in the following form

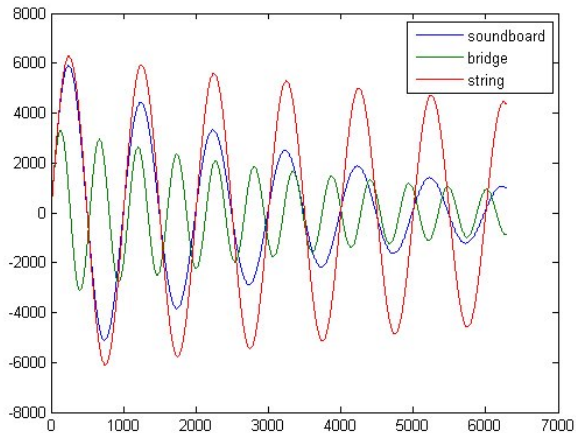
$$M\ddot{x} + C\dot{x} + Kx$$

With

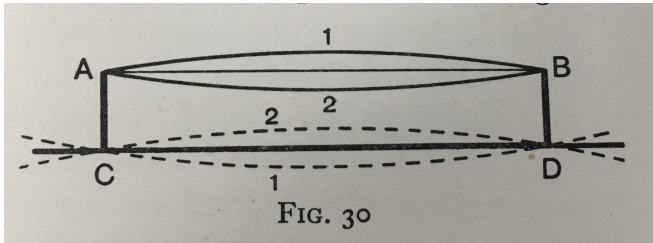
$$M = \begin{bmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{bmatrix} \quad C = \begin{bmatrix} -c_1 - c_2 & c_2 & 0 \\ c_2 & -c_2 - c_3 & c_3 \\ 0 & c_3 & -c_3 \end{bmatrix}$$

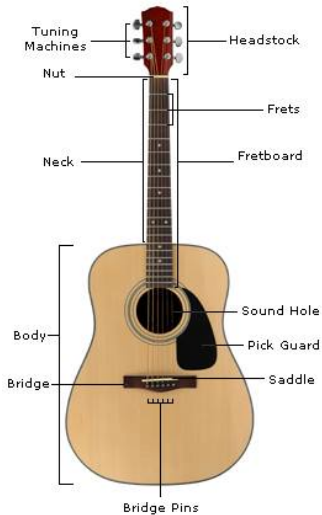
$$K = \begin{bmatrix} k_1 + k_2 & -k_2 & 0 \\ -k_2 & k_2 + k_3 & -k_3 \\ 0 & -k_3 & k_3 \end{bmatrix} \quad \ddot{x} = \begin{bmatrix} \ddot{x}_1 \\ \ddot{x}_2 \\ \ddot{x}_3 \end{bmatrix} \quad \dot{x} = \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

# Sound Plot

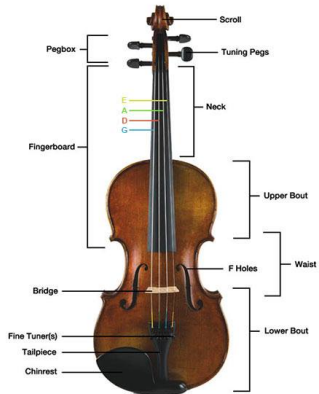


# String, bridge and soundboard





Guitar



violin





harp



piano bridge

# References



A.B.Wood : A Text-book of Sound