

§3 Numerical Integration

**§3.1 Introduction / Newton-Cotes / The Trapezium Rule**

MA378/531 – Numerical Analysis II (“NA2”)

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**Problem**

*Given a real-valued function  $f$  that is continuous on  $[a, b]$ , can we find an estimate for*

$$I(f) := \int_a^b f(x)dx?$$

*And if we can, can we say how accurate it is?*

Why bother?

- Many problems in applicable mathematics require definite integrals to be evaluated. (These methods were originally motivated by problems in astronomy).
- Evaluating them by finding the anti-derivative can be hard, and very hard to automate.
- Some times, although the function is integrable, its anti-derivative doesn't exist in a closed form.

The process of numerically estimating a definite integral is called ***Numerical Integration*** or ***Quadrature***.

The formulae we'll derive all look like

$$Q_n(f) := q_0 f(x_0) + q_1 f(x_1) + q_2 f(x_2) + \cdots + q_n f(x_n).$$

Here the points  $x_i$  are called *quadrature points* and the  $q_i$  are *quadrature weights*.

We need a way of choosing these.

The simplest approach is to take the points to be equally spaced, i.e.,  $x_i = a + hi$  where  $h = (b - a)/n$ .

## How to choose the weights?

We've spent quite a while talking and thinking about approximating functions with polynomials. So why not find a polynomial interpolant to  $f$  and take the integral of that to be the answer? The appeal of this approach is due to the fact that

- Finding polynomial interpolants is easy.
- Integrating polynomials is easy.
- We can estimate the error easily (yet again, we'll make use of Cauchy's Theorem).

This leads to the **Newton-Cotes** methods, which are the subject of this section, and the next one. Later again, we'll look at more sophisticated methods, called **Gaussian Methods** which use non-uniformly spaced points.

**Definition (Newton-Cotes quadrature)**

The **Newton-Cotes** quadrature rule for  $\int_a^b f(x)dx$  with  $n + 1$  points is derived by integrating exactly the polynomial of degree  $n$  that interpolates  $f$  at the  $n + 1$  equally spaced points  $a = x_0 < x_1 < \cdots < x_n = b$ . The method is written as

$$Q_n(f) := q_0 f_0 + q_1 f_1 + q_2 f_2 + \cdots + q_n f_n,$$

where we use the notation  $f_k := f(x_k)$ .

That is, the quadrature weights are chosen so that

$$Q_n(f) = \int_a^b p_n(x)dx,$$

where  $p_n$  is the polynomial of degree  $n$  that interpolates  $f$  at the  $n + 1$  quadrature points...

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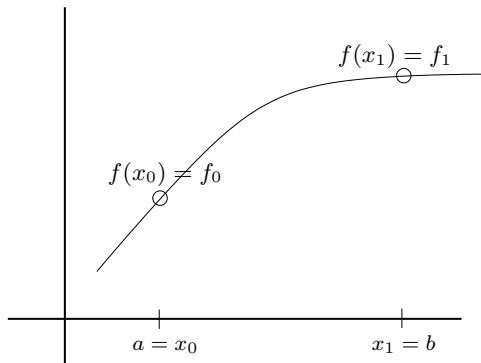
However, it turns out that we can compute the weights  $q_0, q_1, \dots, q_n$ , **without** knowing  $p_n$ .

We'll do this for  $n = 1$  in the next section, and  $n = 2$  (the most interesting case) in Section 3.2.

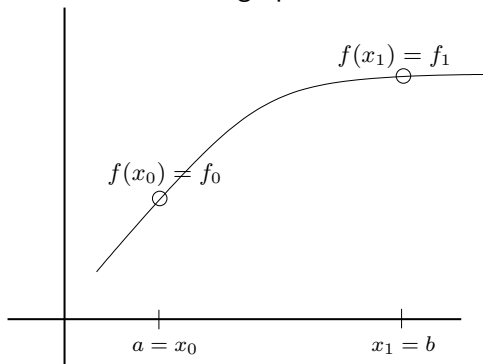
# The Trapezium rule

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Suppose we wanted to estimate the integral of a function,  $f$ , shown below, on the interval  $[a, b]$ .

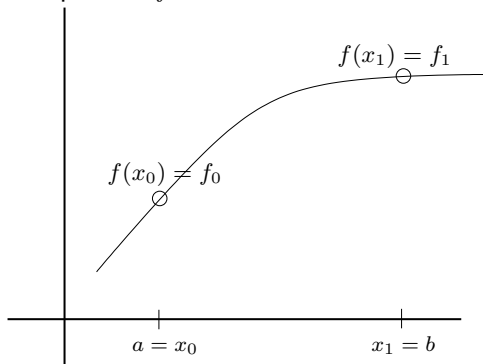


**Method 1:** We could try to estimate the area of the trapezium that fits under the graph:





**Method 2:** We could find  $p_1$ , the polynomial of degree 1 that interpolates  $f$  at  $x = a$  and  $x = b$ :



Note that this shows that  $q_i = \int_a^b L_i(x)dx$ , where, as usual, the  $L_i$  are the Lagrange Polynomials.

**Method 3:** The third approach for generating the Trapezium Rule is called the *Method of Undetermined Coefficients*. Because the method is based on integrating a linear function we expect it to yield an exact solution for any constant or linear function (i.e., there should be no error). To keep the algebra simple, we'll take  $a = 0$  and  $b = 1$ . So,

$$Q_1(f) = q_0 f(0) + q_1 f(1),$$

and, setting  $f(x) \equiv 1$ , and then  $f(x) = x$  we get

Now we need to extend this to estimating  $\int_a^b g(x)dx$  as follows:

### Example

Use the trapezoid to estimate

$$\int_0^{\pi/4} \cos(x) dx.$$

Calculate the (exact) error  $|\int_a^b f(x) dx - Q_1(f)|$ .