

## 1.4 Computing the polynomial interpolant

### 1.4.1 Synthetic Division

The Lagrange form of the polynomial interpolant has great theoretical importance. It is also useful for  $n = 0, 1, 2$ , say. In practice, for larger  $n$ , it is easy to write down the Lagrange form of the polynomial interpolant, but it is tedious (and computationally expensive) to work with. Evaluating each of the

$$L_i(x) = \prod_{j=0, j \neq i}^n \frac{x - x_j}{x_i - x_j}$$

at a given value of  $x$  requires  $2n - 1$  multiplications. So therefore computing

$$p_n(x) = \sum_{i=0}^n y_i L_i(x) = \sum_{i=0}^n \left( y_i \prod_{j=0, j \neq i}^n \frac{x - x_j}{x_i - x_j} \right),$$

for a given value of  $x$  requires  $2n^2 + 2n$  multiplications. On the other hand, suppose we have  $p_n$  in the standard form

$$p_n(x) = a_0 + a_1x + a_2x^2 + \cdots + a_nx^n.$$

At first glance it seems that this takes  $(n^2 - n)/2$  multiplications, which is only a little better. However there is a faster way of doing this called *synthetic division*. As an example we'll consider how this works for the case  $n = 3$ . For the general case, please have a look at [S96, Lecture 19].

Take notes:

In summary,

- The Lagrange form is easy to find and difficult to evaluate.
- The standard form (i.e.,  $p_n = a_0 + a_1x + \cdots + a_nx^n$ ), is hard to find, but easy to evaluate.
- So we want to find a form for the polynomial is easy to construct *and* efficient to evaluate.

There are plenty of possibilities – too many to mention – and we'll consider one of them: the *Newton Form*.

### 1.4.2 The Newton Form of the Interpolant

**This section is just for your information: it will not be covered in class or be part of any assessment.**

These notes are based on §2.1.3 of [SB92] and on [S96, Lecture 19].

Suppose we were to write the interpolating polynomial  $p_n$  as

$$\begin{aligned} p_n(x) = & a_0 + a_1(x - x_0) \\ & + a_2(x - x_0)(x - x_1) \\ & + a_3(x - x_0)(x - x_1)(x - x_2) \\ & + \cdots + a_n(x - x_0)(x - x_1) \cdots (x - x_{n-1}). \end{aligned}$$

Then it could actually be evaluated as

$$\begin{aligned} p_n(x) = & a_0 + \\ & (x - x_0) \left( a_1 + (x - x_1) (a_2 + (x - x_2) (a_3 + \right. \\ & \left. (\cdots + a_n(x - x_{n-1})) \cdots) \right). \end{aligned} \quad (1.9)$$

This is called the *Newton Form of the Interpolating Polynomial*.<sup>8</sup>

Let  $\pi_k$  be the nodal polynomial  $\pi_k = \prod_{i=0}^k (x - x_i)$ . Then the Newton form is

$$p_n(x) = a_0 + a_1\pi_0 + a_2\pi_1 + a_3\pi_2 + \cdots + a_n\pi_{n-1}.$$

So how do we find the coefficients? Let

$$F[x_i] = f(x_i),$$

$$F[x_i, x_{i+1}] = \frac{F[x_{i+1}] - F[x_i]}{x_{i+1} - x_i}$$

⋮

$$\begin{aligned} F[x_i, x_{i+1}, \dots, x_{i+k}] = \\ \frac{F[x_{i+1}, x_{i+2}, \dots, x_{i+k}] - F[x_i, x_{i+1}, \dots, x_{i+k-1}]}{x_{i+k} - x_i} \end{aligned}$$

Then

$$a_0 = f[x_0], \quad a_1 = F[x_0, x_1], \quad \dots$$

$$a_n = F[x_0, x_1, \dots, x_n].$$

Or, if you prefer:

$$p_n(x) = F[x_0] + \sum_{k=1}^n F[x_0, x_1, \dots, x_k] \pi_k(x). \quad (1.10)$$



Sir Issac Newton Isaac Newton, 1643 - 1727, England. Easily one of the greatest scientist of all time. This image is of a Polish stamp commemorating the scientific achievements. Source: <http://jeff560.tripod.com/stamps.html>

It is not hard to show that the formula given in (1.10) yields the interpolating polynomial. The argument is inductive. Before we do that, we will demonstrate that it works for a particular example.

**Example 1.4.1.** Write down the Newton form of the polynomial  $p_2$  that interpolates  $e^x$  at  $x_0 = 0$ ,  $x_1 = 1$  and  $x_2 = 2$ .

**Solution:** (For the Newton form)

	$F[x_i]$	$F[x_i x_{i+1}]$	$F[x_i x_{i+1} x_{i+2}]$
$x_0$	1		
$x_1$	$e$	$e - 1$	
$x_2$	$e^2$	$e^2 - e$	$\frac{1}{2}(e^2 - 2e + 1)$

This gives

$$\begin{aligned} p_2(x) &= F[x_0] + (x - x_0)(F[x_0 x_1] + (x - x_1)F[x_0 x_1 x_2]), \\ &= 1 + x((e - 1) + (x - 2)\frac{1}{2}(e^2 - 2e + 1)). \end{aligned}$$

Written in the form of (1.10) above, this is

$$p_2(x) = 1 + (e - 1)(x) + \frac{1}{2}(e^2 - 2e + 1)(x)(x - 1).$$

One can quickly check that this

1. is a polynomial of degree  $n$ ,
2. interpolates  $e^x$  at  $x = 0$ ,  $x = 1$  and  $x = 2$ .

It is not hard to show that the formula given in (1.10) yields the interpolating polynomial. The argument is inductive. Clearly its true for  $n = 0$ , because in that case the interpolant is just the constant polynomial  $p_0 = F[x_0] = f(x_0)$ .

Next, suppose it is true for  $n$  points. Then let

- $p_n$  interpolate  $f(x)$  at  $x = x_0, x_1, \dots, x_n$ ,
- $q_{n-1}(x)$  interpolate  $f(x)$  at  $x = x_0, x_1, \dots, x_{n-1}$ ,
- $r_{n-1}(x)$  interpolate  $f(x)$  at  $x = x_1, x_2, \dots, x_n$ .

We must convince ourselves that

$$p_n(x) = q_{n-1}(x) + \frac{x - x_0}{x_n - x_0}(r_{n-1}(x) - q_{n-1}(x)),$$

First, since both  $q_{n-1}$  and  $r_{n-1}$  are polynomials of degree  $n - 1$ , it follows that the expression on the right is indeed a polynomial of degree  $n$ .

Next, check that it is the interpolant of  $f$  at  $x_0, x_1, \dots, x_n$ . For the first point,  $x_0$ :

$$\begin{aligned} p_n(x_0) &= q_{n-1}(x_0) + \frac{x_0 - x_0}{x_n - x_0}(r_{n-1}(x_0) - q_{n-1}(x_0)) \\ &= q_{n-1}(x_0) = f(x_0). \end{aligned}$$

For the last point,  $x_n$ :

$$\begin{aligned} p_n(x_n) &= q_{n-1}(x_n) + \frac{x_n - x_0}{x_n - x_0}(r_{n-1}(x_n) - q_{n-1}(x_n)) \\ &= q_{n-1}(x_n) + (r_{n-1}(x_n) - q_{n-1}(x_n)) \\ &= r_{n-1}(x_n) = f(x_n). \end{aligned}$$

And for every other point,  $x_i$ ,  $i = 1, \dots, n - 1$ ,

$$\begin{aligned} p_n(x_i) &= q_{n-1}(x_i) + \frac{x_i - x_0}{x_n - x_0}(r_{n-1}(x_i) - q_{n-1}(x_i)) \\ &= f(x_i) + \frac{x_i - x_0}{x_n - x_0}(f(x_i) - f(x_i)) = f(x_i). \end{aligned}$$

Finally, we need to compare the coefficient of  $x^n$  on the left- and right-hand sides of this equations.

The coefficient of  $x^{n-1}$  in  $q_{n-1}$  is  $F[x_0, x_1, \dots, x_{n-1}]$ . The coefficient of  $x^{n-1}$  in  $r_{n-1}$  is  $F[x_1, x_2, \dots, x_n]$ . So the coefficient of  $x^n$  in  $p_n$  is

$$\frac{1}{x_n - x_0}(F[x_1, x_2, \dots, x_n] - F[x_0, x_1, \dots, x_{n-1}]),$$

as required.

### 1.4.3 Exercise

**Exercise 1.12.** Do Exercise 6.3 from Süli and Mayers, *An Introduction to Numerical Analysis*.