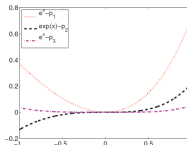
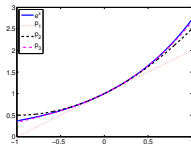


§0. Introduction to MA385; Taylor's Theorem

§0.2 Taylor's Theorem

MA385/530 – Numerical Analysis 1

September 2017



Taylor's Theorem is perhaps the most important mathematical tool in Numerical Analysis. Providing we can evaluate the derivatives of a given function at some point, it gives us a way of approximating the function by a polynomial.

Working with polynomials, particularly ones of degree 3 or less, is much easier than working with arbitrary functions. For example, polynomials are easy to differentiate and integrate. Most importantly for the next section of this course, their zeros are easy to find.

Our starting point is the classic *mean value theorem*.

Theorem (Mean Value Theorem)

If f is function that is continuous and differentiable for all $a \leq x \leq b$, then there is a point $c \in [a, b]$ such that

$$\frac{f(b) - f(a)}{b - a} = f'(c).$$

This is just a consequence of Rolle's Theorem, and has few different interpretations. One is that the slope of the line that intersects f at the points a and b is equal to the slope of the tangent to f at some point between a and b .

Right now, we are interested in the fact that the MVT tells us that we can approximate the value of a function by a near-by value, with accuracy that depends on f' :

Or we can think of it as approximating f by a line:

What if we want a better approximation? We could replace our function with a quadratic polynomial. For example, let

$$p_2(x) = b_0 + b_1(x - a) + b_2(x - a)^2,$$

and solve for the coefficients b_0 , b_1 and b_2 so that

$$p_2(a) = f(a), \quad p_2'(a) = f'(a), \quad p_2''(a) = f''(a).$$

Next, if we try to construct an approximating cubic of the form

$$\begin{aligned} p_3(x) &= b_0 + b_1(x - a) + b_2(x - a)^2 + b_3(x - a)^3, \\ &= \sum_{k=0}^3 b_k(x - a)^k, \end{aligned}$$

with the property that

$$\begin{aligned} p_3(a) &= f(a), & p_3'(a) &= f'(a), \\ p_3''(a) &= f''(a), & p_3'''(a) &= f'''(a). \end{aligned} \tag{1}$$

Again we find that

$$b_k = \frac{f^{(k)}}{k!} \quad \text{for } k = 0, 1, 2, 3.$$

Definition (Taylor Polynomial)

The *Taylor Polynomial* of degree k (also called the *Truncated Taylor Series*) that approximates the function f about the point $x = a$ is

$$p_k(x) = f(a) + (x - a)f'(a) + \frac{(x - a)^2}{2}f''(a) + \frac{(x - a)^3}{3!}f'''(a) + \cdots + \frac{(x - a)^k}{k!}f^{(k)}(a).$$

Brook Taylor, 1665 – 1731, England. He (re)discovered this polynomial approximation in 1712, though its importance was not realised for another 50 years.



Example

Write down the Taylor polynomial of degree k that approximates $f(x) = e^x$ about the point $x = 0$.

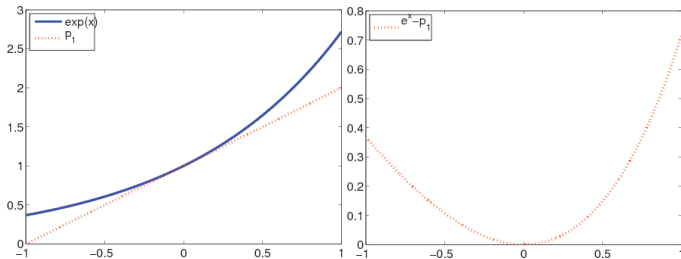


Figure: Taylor polys for $f(x) = e^x$ about $x = 0$ (left), and errors (right)

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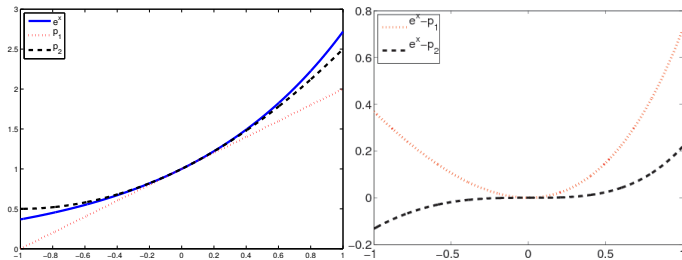


Figure: Taylor polys for $f(x) = e^x$ about $x = 0$ (left), and errors (right)

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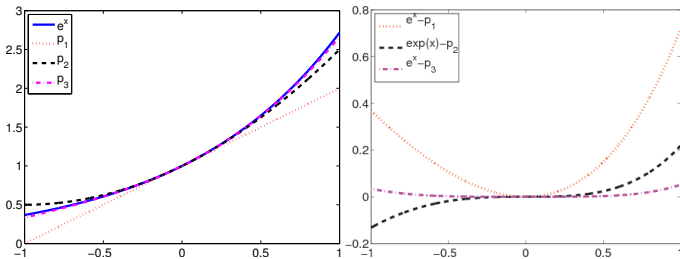


Figure: Taylor polys for $f(x) = e^x$ about $x = 0$ (left), and errors (right)

We now want to examine the *accuracy* of the Taylor polynomial as an approximation. In particular, we would like to find a formula for the *remainder* or *error*:

$$R_k(x) := f(x) - p_k(x).$$

With a little bit of effort one can prove that:

$$R_k(x) := \frac{(x-a)^{k+1}}{(k+1)!} f^{(k+1)}(\sigma), \text{ for some } \sigma \in [x, a].$$

We won't prove this in class. But for the sake of completeness, a proof is included in the notes.

Example

With $f(x) = e^x$ and $a = 0$, we get that

$$R_k(x) = \frac{x^{k+1}}{(k+1)!} e^\sigma, \text{ some } \sigma \in [0, x].$$

Example

How many terms are required in the Taylor Polynomial for e^x about $x = 0$ to ensure that the error at $x = 1$ is

- no more than 10^{-1} ?
- no more than 10^{-2} ?
- no more than 10^{-6} ?
- no more than 10^{-10} ?

The reasons for emphasising Taylor's theorem so early in this course are that

- It introduces us to the concept of approximation, and error estimation, but in a very simple setting;
- It is the basis for deriving methods for solving both nonlinear equations, and initial value ordinary differential equations.

With the last point in mind, we'll now outline how to derive Newton's method for nonlinear equations.

