Chapter 4

Markov Processes

4.1 Markov Processes and Markov Chains

Recall the following example from Section 3.1.

Two competing Broadband companies, A and B, each currently have 50% of the market share. Suppose that over each year, A captures 10% of B’s share of the market, and B captures 20% of A’s share.

This situation can be modelled as follows. Let $a_n$ and $b_n$ denote the proportion of the market held by A and N respectively at the end of the $n$th year. We have $a_0 = b_0 = 0.5$ (beginning of Year 1 = end of Year 0).

Now $a_{n+1}$ and $b_{n+1}$ depend on $a_n$ and $b_n$ according to

$$
\begin{align*}
a_{n+1} &= 0.8a_n + 0.1b_n \\
b_{n+1} &= 0.2a_n + 0.9b_n
\end{align*}
$$

We can write this in matrix form as follows

$$
\begin{pmatrix}
a_{n+1} \\
b_{n+1}
\end{pmatrix} = \begin{pmatrix} 0.8 & 0.1 \\ 0.2 & 0.9 \end{pmatrix} \begin{pmatrix} a_n \\ b_n \end{pmatrix}.
$$

We define $M = \begin{pmatrix} 0.8 & 0.1 \\ 0.2 & 0.9 \end{pmatrix}$. Note that every entry in $M$ is non-negative and that the sum of the entries in each column is 1. This is no accident since the entries in the first column of $M$ are the respective proportions of A’s market share that are retained and lost respectively by A from one year to the next. Column 2 contains similar data for B.
Definition 4.1.1 A stochastic matrix is a square matrix with the following properties:

(i) All entries are non-negative.

(ii) The sum of the entries in each column is 1.

So the matrix $M$ of our example is stochastic.

Returning to the example, if we let $v_n$ denote the vector \[
\begin{pmatrix}
a_n \\
b_n 
\end{pmatrix}
\] describing the position at the end of year $n$, we have

\[
v_0 = \begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix}, \quad v_1 = Mv_0, \quad v_{n+1} = Mv_n.
\]

Note that the sum of the entries in each $v_i$ is 1.

Definition 4.1.2 A column vector with non-negative entries whose sum is 1 is called a probability vector.

It is not difficult to see that if $v$ is a probability vector and $A$ is a stochastic matrix, then $Av$ is a probability vector. In our example, the sequence $v_0, v_1, v_2, \ldots$ of probability vectors is an example of a Markov Chain. In algebraic terms a Markov chain is determined by a probability vector $v$ and a stochastic matrix $A$ (called the transition matrix of the process or chain). The chain itself is the sequence

\[
v_0, \quad v_1 = Av_0, \quad v_2 = Av_3, \ldots
\]

More generally a Markov process is a process in which the probability of observing a particular state at a given observation period depends only on the state observed at the preceding observation period.

Remark: Suppose that $A$ is a stochastic matrix. Then from Item 5 in Section 3.4 it follows that 1 is an eigenvalue of $A$ (all the columns of $A$ sum to 1). The transition matrix in our example is

\[
M = \begin{pmatrix} 0.8 & 0.1 \\ 0.2 & 0.9 \end{pmatrix}.
\]

Eigenvectors of $M$ corresponding to the eigenvalue 1 are non-zero vectors \[
\begin{pmatrix} x \\ y \end{pmatrix}
\] for which

\[
\begin{pmatrix} 0.8 & 0.1 \\ 0.2 & 0.9 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}
\]

63
Thus
\[
\begin{align*}
0.8x + 0.1y &= x \\
0.2x + 0.9y &= y
\end{align*}
\implies y = 2x.
\]

So any non-zero vector of the form \( \begin{pmatrix} x \\ 2x \end{pmatrix} \) is an eigenvector of \( M \) corresponding to the eigenvalue 1. Amongst all these vectors exactly one is a probability vector, namely the one with \( x + 2x = 1 \), i.e. \( x = \frac{1}{3} \). This eigenvector is \( \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \).

The Markov process in our example is \( v_0, v_1, v_2, \ldots \), where \( v_0 = \begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix} \) and \( v_{i+1} = M v_i \).

We can observe
\[
\begin{align*}
v_5 &= M^5 v_0 \approx \begin{pmatrix} 0.3613 \\ 0.6887 \end{pmatrix} \\
v_{10} &= M^{10} v_0 \approx \begin{pmatrix} 0.3380 \\ 0.6620 \end{pmatrix} \\
v_{20} &= M^{20} v_0 \approx \begin{pmatrix} 0.3335 \\ 0.6665 \end{pmatrix} \\
v_{30} &= M^{30} v_0 \approx \begin{pmatrix} 0.3333 \\ 0.6667 \end{pmatrix}
\end{align*}
\]

So it appears that the vectors in the Markov chain approach the eigenvector \( \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \) of \( M \) as the process develops. This vector is called the *steady state* of the process.

This example is indicative of a general principle.

**Definition 4.1.3** A stochastic \( n \times n \) matrix \( M \) is called regular if \( M \) itself or some power of \( M \) has all entries positive (i.e. no zero entries).

**Example**

- \( M = \begin{pmatrix} 0.8 & 0.1 \\ 0.2 & 0.9 \end{pmatrix} \) is a regular stochastic matrix.
• $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ is a stochastic matrix but it is not regular:

$$A^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \ A^3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = A,$$ etc

The positive powers of $A$ just alternate between $I_2$ and $A$ itself. So no positive integer power of $A$ is without zero entries.

**Theorem 4.1.4** Suppose that $A$ is a regular stochastic $n \times n$ matrix. Then

• There is a unique probability vector $v$ for which $Av = v$.

• If $u_0$ is any probability vector then the Markov chain $u_0, u_1, \ldots$ defined for $i \geq 1$ by $u_i = Au_{i-1}$ converges to $v$.

(This means that for $1 \leq i \leq n$, the sequence of the $i$th entries of $u_0, u_1, u_2, \ldots$ converges to the $i$th entry of $v$).

**Notes**

1. **Theorem 4.1.4** says that if a Markov process has a regular transition matrix, the process will converge to the steady state $v$ regardless of the initial position.

2. **Theorem 4.1.4** does not apply when the transition matrix is not regular. For example if $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and $u_0 = \begin{pmatrix} a \\ b \end{pmatrix}$ $(a \neq b)$ is a probability vector, consider the Markov chain with initial state $u_0$ that has $A$ as a transition matrix.

$$u_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} b \\ a \end{pmatrix}, \ u_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} b \\ a \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}.$$ This Markov chain will switch between $\begin{pmatrix} a \\ b \end{pmatrix}$ and $\begin{pmatrix} b \\ a \end{pmatrix}$ and not converge to a steady state.

**Example 4.1.5** *(Summer 2004 Q4)* An airline has planes based in Knock, Cork and Shannon. Each week $\frac{1}{4}$ of the planes originally based in Galway end up in Knock and $\frac{1}{3}$ end up in Shannon - the rest return to Galway.
Of the planes starting the week in Knock, \( \frac{5}{12} \) end up in Galway and \( \frac{1}{10} \) in Shannon. The rest return to Knock.

Finally, of the planes starting the week in Shannon, \( \frac{1}{5} \) end up in Galway and \( \frac{1}{5} \), the rest returning to Shannon.

Find the steady state of this Markov process.

Solution: The Markov process is a sequence \( v_1, v_2, \ldots \) of column vectors of length 3. The entries of the vector \( v_i \) are the proportions of the airline’s fleet that are located at Galway, Knock and Shannon at the end of Week \( i \). They are related by

\[
v_{i+1} = M v_i,
\]

where \( M \) is the transition matrix of the process.

Step 1: Write down the transition matrix. If we let \( g_i, k_i, s_i \) denote the proportion of the airline’s fleet at Galway, Knock and Shannon after Week \( i \), we have

\[
\begin{align*}
g_{i+1} &= \frac{5}{12}g_i + \frac{1}{5}k_i + \frac{1}{5}s_i \\
k_{i+1} &= \frac{1}{4}g_i + \frac{7}{10}k_i + \frac{1}{5}s_i \\
s_{i+1} &= \frac{1}{3}g_i + \frac{1}{10}k_i + \frac{3}{5}s_i
\end{align*}
\]

Thus

\[
v_{i+1} = \begin{pmatrix} g_{i+1} \\ k_{i+1} \\ s_{i+1} \end{pmatrix} = \begin{pmatrix} \frac{5}{12} & \frac{1}{5} & \frac{1}{5} \\ \frac{1}{4} & \frac{7}{10} & \frac{1}{5} \\ \frac{1}{3} & \frac{1}{10} & \frac{3}{5} \end{pmatrix} \begin{pmatrix} g_i \\ k_i \\ s_i \end{pmatrix} = M v_i.
\]

\( M \) is the transition matrix of the process.

Note: If the rows and columns of \( M \) are labelled \( G, K, S \) for Galway, Knock and Shannon, then the entry in the \( (i, j) \) position is the proportion of those planes that start the week in the airport labelling Column \( j \) which finish the week in the airport labelling Row \( i \). Note that \( M \) is a regular stochastic matrix.

Step 2: The steady state of the process is the unique eigenvector of \( m \) with eigenvalue 1 that is a probability vector. To calculate this we need to solve the system of equations whose coefficient
matrix is \( M - I_3 \) (and which has zeroes on the right). The coefficient matrix is

\[
M - I_3 = \begin{pmatrix}
-\frac{7}{12} & \frac{1}{5} & \frac{1}{5} \\
\frac{1}{3} & -\frac{3}{10} & \frac{1}{5} \\
\frac{1}{3} & \frac{1}{10} & -\frac{2}{5}
\end{pmatrix}
\]

**Remark:** If \( A \) is a stochastic matrix (transition matrix), then the sum of the entries in each column of \( A \) is 1. It follows that the sum of the entries in each column of \( A - I \) is 0, since \( A - I \) is obtained from \( A \) by subtracting 1 from exactly one entry of each column. So the sum of the rows of \( A - I \) is the row full of zeroes. This means that in reducing \( A - I \) to reduced row echelon form, we can begin by simply eliminating one of the rows (by adding the sum of the remaining rows to it).

We proceed as follows with elementary row operations on the matrix \( M - I \).

\[
\begin{pmatrix}
-\frac{7}{12} & \frac{1}{5} & \frac{1}{5} \\
\frac{1}{3} & -\frac{3}{10} & \frac{1}{5} \\
\frac{1}{3} & \frac{1}{10} & -\frac{2}{5}
\end{pmatrix} \quad R1 \leftrightarrow R3 \quad \rightarrow \quad \begin{pmatrix}
\frac{1}{3} & \frac{1}{10} & -\frac{2}{5} \\
\frac{1}{3} & -\frac{3}{10} & \frac{1}{5} \\
\frac{7}{12} & \frac{1}{5} & \frac{1}{5}
\end{pmatrix}
\]

\[
R3 \rightarrow R3 + (R1 + R2) \quad \rightarrow \quad \begin{pmatrix}
\frac{1}{3} & \frac{1}{10} & -\frac{2}{5} \\
\frac{1}{3} & -\frac{3}{10} & \frac{1}{5} \\
0 & 0 & 0
\end{pmatrix} \quad R1 \times 3 \quad \rightarrow \quad \begin{pmatrix}
1 & \frac{3}{10} & -\frac{6}{5} \\
1 & -\frac{12}{10} & \frac{4}{5} \\
0 & 0 & 0
\end{pmatrix}
\]

\[
R2 \rightarrow R2 - R1 \quad \rightarrow \quad \begin{pmatrix}
1 & \frac{3}{10} & -\frac{6}{5} \\
0 & -\frac{15}{10} & 2 \\
0 & 0 & 0
\end{pmatrix} \quad R2 \times \left(-\frac{2}{3}\right) \quad \rightarrow \quad \begin{pmatrix}
1 & \frac{3}{10} & -\frac{6}{5} \\
0 & 1 & -\frac{4}{3} \\
0 & 0 & 0
\end{pmatrix}
\]

\[
R1 \rightarrow R1 - (3/10)R2 \quad \rightarrow \quad \begin{pmatrix}
1 & 0 & -\frac{1}{3} \\
0 & 1 & -\frac{1}{3} \\
0 & 0 & 0
\end{pmatrix}
\]

Thus any vector \( \begin{pmatrix} x \\ y \\ z \end{pmatrix} \) satisfying \( x = \frac{4}{5}z \) and \( y = \frac{4}{3}z \) is an eigenvector of \( M \) corresponding to the eigenvalue \( \lambda = 1 \). We need the unique such eigenvector in which the sum of the entries
is 1, i.e.

\[ \frac{4}{5}z + \frac{4}{3}z + z = 1 \implies \frac{47}{15}z = 1. \]

Thus \( z = \frac{15}{47} \), and the steady state vector is

\[
\begin{pmatrix}
12 \\
20 \\
15
\end{pmatrix}_{47}.
\]