

# THE GROUP OF SYMMETRIES OF THE CUBE

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## Introduction

The cube is a shape made up of 6 faces, 8 vertices and 12 edges. The cube has 24 rotational symmetries and they form a group that is a copy of  $S_4$ , the group of permutations of four objects. It also has 24 reflections among the 9 planes of reflection. This makes up in total the 48 isometries of the cube.

All 24 permutations of the diagonals can be generated by any 2 rotations

Let the rotation  $A$  be a rotation clockwise about the vertical axis (as shown in the diagram) and Rotation  $B$  be a rotation about the horizontal axis.

- Rotation  $A$  ( $R_A$ )-

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 2 & 3 & 4 & 1 & 6 & 7 & 8 & 5 \end{pmatrix}$$

i.e the rotation takes 1 -> 2 for example

- Rotation  $B$  ( $R_B$ )-

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 2 & 6 & 7 & 3 & 1 & 5 & 8 & 4 \end{pmatrix}$$

i.e the rotation takes 3 -> 7 for example

Now we can combine both of these matrices of permutations to generate another, and/or combine it with itself multiple times to get different permutations. For Example,

■  $(R_A)^2 =$

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 2 & 3 & 4 & 1 & 6 & 7 & 8 & 5 \end{pmatrix} \times \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 2 & 3 & 4 & 1 & 6 & 7 & 8 & 5 \end{pmatrix}$$

Notice here that 1 -> 2 -> 3, i.e 1 -> 3

□  $(R_A)^3$  also produces a new permutation, i.e sending 3 -> 4 -> 1 -> 2, i.e 3 -> 2.

□ Same goes for  $(R_B)^2, (R_B)^3$ , But when you apply a rotation a 4th time, i.e  $(R_A)^4$  or  $(R_B)^4$ , each vertex returns to its original position, also know as the identity rotation ( $I$ ).

■ We can now induce a subgroup of order 8 =  $\{ I, R_A, (R_A)^2, (R_A)^3, (R_B)^2, (R_B)^2 R_A, (R_B)^2 (R_A)^2, (R_B)^2 (R_A)^3 \}$

■ And a subgroup of order 3  $\{ I, R_A R_B, (R_A R_B)^2 \}$

■ Calculating the *LowestCommonMultiple* (*lcm*) of both orders of the subgroups give you 24, i.e the number of all permutations generated by 2 rotations.

## Graphical Visualisation

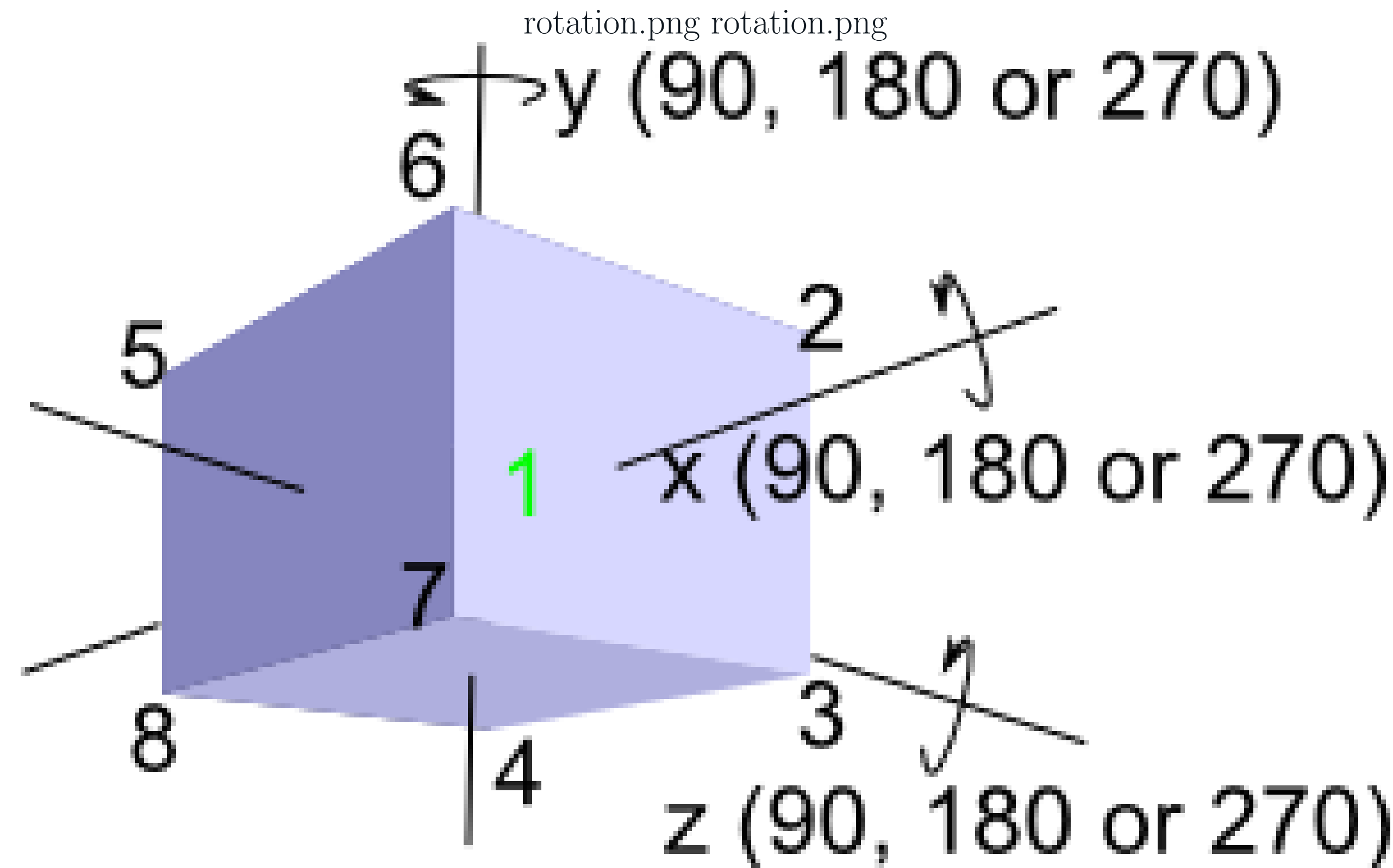


Fig. 1: The Rotations of The Cube

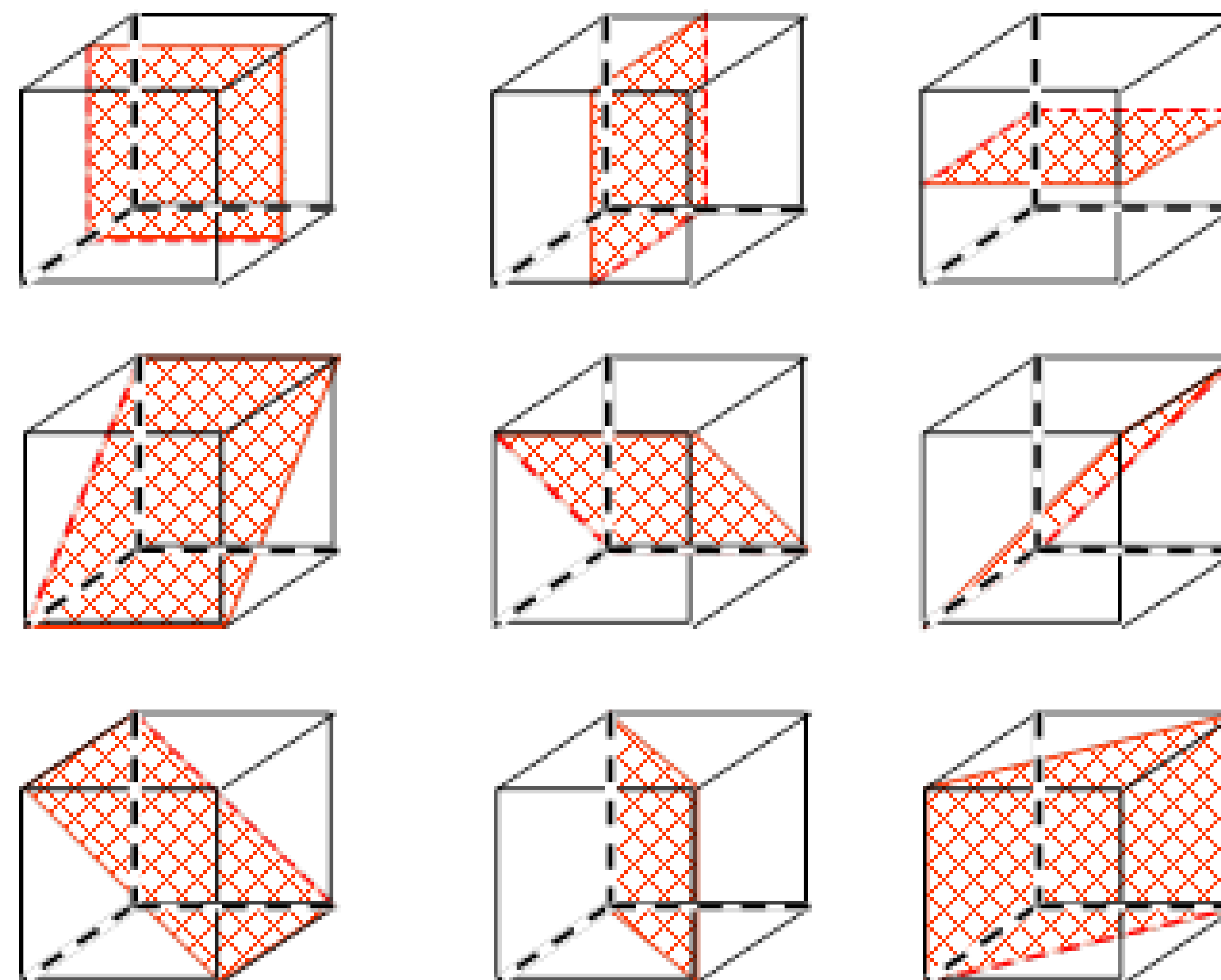


Fig. 2: The Reflection Planes of The Cube

## Rotational Matrices

Take a set of all 3x3 permutation matrices and assign a + or a - to each of the 1's in the matrix. There are 6 matrices and 8 different sign permutations, that's 48 matrices in total giving the whole group of symmetries of the cube. There are exactly 24 matrices with determinant = +1 and these are the rotational matrices of the octahedral group.

$$\begin{pmatrix} +1 & 0 & 0 \\ 0 & 0 & +1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} +1 & 0 & 0 \\ 0 & +1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

The other 24 matrices with determinant of -1 correspond to a reflection or inversion.

$$\begin{pmatrix} +1 & 0 & 0 \\ 0 & 0 & +1 \\ 0 & +1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & +1 & 0 \\ +1 & 0 & 0 \\ 0 & 0 & +1 \end{pmatrix}$$

## Orbit Stabilizer Theorem

Let  $G$  be a group that acts on a set  $X$ , let  $x$  be an element of  $X$ , let  $O_x$  be the orbit of  $x$  and let  $S_x$  be the stabilizer of  $x$ . Then  $|O_x||S_x| = |G|$ .

In words, the size of the group is the size of the orbit times the size of the stabilizer.

Proof: Here are two equivalence relations on  $G$ . For the first, I define  $g \sim_1 h$  if  $gx = hx$ . For the second, I define  $g \sim_2 h$  if  $h^{-1}g \in S_x$ . Note that this is the same as saying that  $g^{-1}h \in S_x$  and also the same as saying that  $gS_x = hS_x$ .

Now  $gx = hx$  if and only if  $h^{-1}gx = x$  if and only if  $h^{-1}g \in S_x$ . So the two equivalence relations are the same. The number of equivalence classes for the first relation is  $|O_x|$  and the size of each equivalence class for the second relation is obviously  $|S_x|$ , so the result is proved.

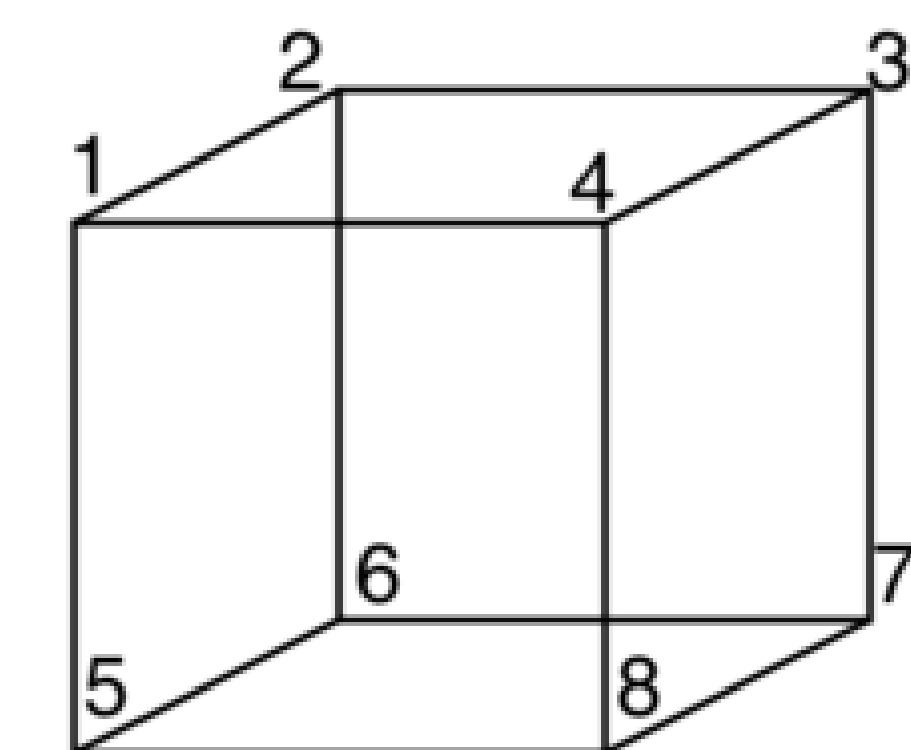


Fig. 3: Points of Orbit of the Cube